ingenuity@work®

GURLEY SERIES VL18 VIRTUAL ABSOLUTE ENCODER

MOTION TYPE:

LINEAR

USAGE GRADE:

INDUSTRIAL

OUTPUT:

*VIRTUAL ABSOLUTE

MAX RESOLUTION:

*1.0 UM OR 1/4 UM



*WITH APPROPRIATE ELECTRONICS

BUILT IN TESTING - ABSOLUTE OUTPUT

The **Model VL18** combines the opto-mechanical simplicity and ruggedness of an incremental encoder with the interfacing ease of an absolute encoder. Utilizing Gurley's unique **Virtual Absolute** technology, the **VL18** system is less expensive and more reliable than any conventional absolute encoder of comparable resolution and accuracy. Compared with an incremental encoder, the **VL18** system provides greater system reliability and minimizes homing time.

- 1-μm resolution over 1 meter of travel, or ¼-μm resolution over 250 mm.
- Three accuracy grades available
- LED illumination for long life (>100,000 hours)
- Differential photo-detectors for stable signals
- Small number of wires from the encoder
- Differential output for noise immunity







SPECIFICATIONS

| | See Note | Option 1 | Option 2 | | |
|--------------------------------------|----------|---------------|--------------------------------------|--|--|
| Scale pitch, μm | 1 | 32 | 64 | | |
| Initialization distance, mm (in) | | 0.480 (0.019) | 0.768 (0.030) | | |
| Code length, bits | | 15 | 12 | | |
| Final resolution, μm | 1 | 1 | 0.25 | | |
| Max. measuring length, mm | | 1038 | 252 | | |
| Interpolating Decoder to use | | VB | VF | | |
| Maximum operating speed, mm/s (in/s) | 3 | 1000 (40) | 600 (24) | | |
| Accuracy (at 20°C), μm (μin) | 2 | Grade B: | ±3 (±120) ±5 (±200) ±10 (±400) | | |
| Weight, kg (lb) | | 0.4 + 0.6/m | (0.9 + .03/in) | | |
| Driving force, N (oz) | | 1.5 | 5 (6) | | |
| Operating temperature, °C (°F) | | 0 to 50 (3 | 32 to 122) | | |
| Humidity, % rh, non-condensing | | g | 98 | | |
| Shock | | 50 g, | 11 ms | | |
| Vibration | | 15 g, 0- | 2000 Hz | | |
| Sealing | | IP | 254 | | |
| Read Head support | | precision b | all bearings | | |

NOTES:

- 1. These line counts provides 1 μm resolution after interpolation in the **Model VB** Interpolating Decoder, or ¼ μm with the **VF**. By using other line counts, the system can provide resolutions such as 50 μinches. Consult factory for details.
- 2. This is the total encoder error from all sources. Error is defined at the signal transitions and therefore does not include quantization error, which is ±1/2 quantum. ("Quantum" is the final resolution of the encoder.) Accuracy is guaranteed at 20°C.
- 3. This is the maximum speed for full accuracy.

As part of our continuing product improvement program, all specifications are subject to change without notice.





SPECIFICATIONS

INPUT POWER

+5Vdc @180 mA max, available from **VB** or **VF** interpolating decoder. Separate power supply is not required. See **VB** or **VF** data sheet.

OUTPUT WAVEFORMS

Differential buffered sinusoids, 750 mV p-p.

THEORY OF OPERATION-SHORT VERSION

Virtual Absolute (VA) discs and scales are similar to incremental discs and scales in that they contain a cyclic track and an index track. In an incremental encoder, the index occurs at one place in the full travel, but in a VA encoder, the index track is a continuous serial code (similar in appearance to a bar code). You don't know position immediately upon start-up, as you do in a conventional absolute, but after a very short travel, in either direction and starting from anywhere, you know exactly where you are. In the VL18, this initialization distance is 1.93°. From then on, the encoder is truly absolute. (There are ways to build a pseudorandom encoder so that absolute information is available on power-up without initializing, but these techniques require far more complex sensing hardware; they often impose slower operation as well. And none of them offers the sophisticated built-in testing of GPI's Virtual Absolute technology.)

To complete the system, the **VL18**is used with one of Gurley's **Interpolating Decoders**. The size of a credit card, it contains patented high-speed circuitry to decode the special serial index track and interpolation to increase the final resolution. In addition to the natural binary position output, a *Status* bit is provided to tell you when the encoder is initialized. This bit is at a logic high whenever the initializing motion is not yet complete, or when some other problem such as supply voltage interruption, electrical noise, damage, or fouling of the disc interferes with the proper code sequence from the index track. When these self-tests are all satisfied, the status bit is low, indicating the position data output is valid.

Final resolution depends on which version of interpolating decoder is used. With the Model **VB**, final resolution is 16 bits (65,536) measuring steps/rev. With the Model **VF**, final resolution is 19 bits (524,288) measuring steps/rev, but the max speed is lower. Please refer to the **Model VB** or **VF** data sheet for complete details.

ELECTRICAL CONNECTIONS

| Output Functions | Wire Colors Conn. Code P | Pin #, DA-15P Conn. Code Q | Pin #, DE-15P Conn. Code R | Pin #, AMP 102387-1 Conn. Code V | | |
|---------------------|------------------------------------|--------------------------------------|--------------------------------------|--|--|--|
| SIN | Yellow | 8 | 8 | 4 | | |
| / SIN | Brown | 7 | 7 | 3 | | |
| cos | Green | 5 | 5 | 2 | | |
| / cos | Orange | 4 | 4 | 1 | | |
| IND | Blue | 2 | 2 | 5 | | |
| / IND | White | 1 | 1 | 6 | | |
| +V | Red | 10 | 10 | 7 | | |
| Соммон | Black | 13 | 13 | 8 | | |
| CASE | Bare (shield) * | 9 | 9 | 10 | | |

^{*} The bare wire (shield) is connected to the encoder case.

Use connector code **V** if the encoder will be connected to a **VB** or **VF** interpolating decoder.

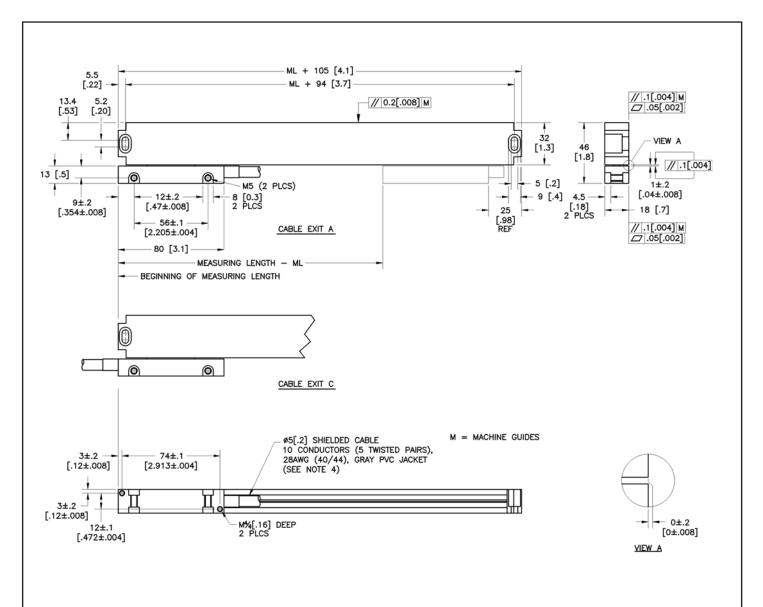
Use connector code **R** if there will be a **CAX###** extension cable between the encoder and the **VB** or **VF** interpolating decoder.

Use connector code **Q** if the encoder will be connected to a Model **DVL** display unit. (The **VB** or **VF** interpolating decoder is inside the DVL.)





SPECIFICATIONS



NOTES:

- 1. ALL DIMENSIONS IN MM [IN].
- 2. STANDARD MEASURING LENGTHS:

| | | | | | | | | | | | | | | | | | 1038 |
|------|-------|------|-----|-----|-----|------|------|------|------|------|------|------|------|------|------|------|------|
| IN | 2.8 | 4.7 | 6.7 | 8.7 | 9.9 | 10.6 | 12.6 | 14.6 | 16.5 | 18.5 | 20.5 | 22.4 | 24.4 | 28.3 | 32.3 | 36.2 | 40.9 |
| CABL | E, IN | CHES | | | | | 60 | | | | | | | | 90 | | |

- 3. READING HEAD HAS 2MM [0.08 IN] MINIMUM OVERTRAVEL AT EACH END.
- 4. FOR CABLE EXIT TO THE LEFT, ORDER EXIT OPTION C.





ORDERING INFORMATION

| VL18 | ACC SO | CALE CODE FORMAT MEAS EXIT TYPE CAB CONN SPEC |
|---------------|------------------|--|
| <u>ACC</u> | A B C | ±3 μm ±5 μm ±10 μm |
| SCALE | 0032M 0064M | 32-µm pitch (use with CODE = 15; order VB electronics) 64-µm pitch (use with CODE = 12; order VF electronics) |
| CODE | 15 12 | Code length = 2^{15} (use with SCALE = 0032M) Code length = 2^{12} (use with SCALE = 0064M) |
| FORMAT | М | Differential analog output |
| MEAS | #### | Measuring length, mm (see drawing note 2) |
| <u>EXIT</u> | A C | Right cable exit (standard) Left cable exit |
| <u>TYPE</u> | S A | Shielded cable (standard) Armored cable |
| CAB | ## 60 90 | Cable length, inches Standard for $\underline{\text{MEAS}} \leq 0570$ Standard for $\underline{\text{MEAS}} > 0570$ |
| CONN | V R Q P | Amp 102387-1; use to connect encoder cable to VB or VF Interpolating Decoder DE-15P; use if there will be a CAX### extension cable between the VL18 and VB or VF DA-15P; use with Model DVL Display Unit Pigtails; no connector |
| <u>SPEC</u> | # N | Issued at time of order to cover special customer requirements No special features |

ACCESSORIES (order separately)

VB Interpolating decoder; use with VL18x0032M... See separate data sheet
VF Interpolating decoder; use with VL18x0064M... See separate data sheet

CAX### Extension cable assembly, ### inches long. (enc. cable + ext. cable = 600 max)

SPECIAL CAPABILITIES

For special situations, we can optimize catalog encoders to provide higher frequency response, greater accuracy, wider temperature range, reduced torque, non-standard line counts, or other modified parameters. In addition, we regularly design and manufacture custom encoders for user-specific requirements. These range from high-volume, low-cost, limited-performance commercial applications to encoders for military, aerospace and similar high-performance, high-reliability conditions. We would welcome the opportunity to help you with your encoder needs.

WARRANTY

Gurley Precision Instruments offers a limited warranty against defects in material and workmanship for a period of one year from the date of shipment.



