# GURLEY SERIES 9X25 ROTARY INCREMENTAL ENCODERS

MOTION TYPE:

ROTARY

**USAGE GRADE:** 

INDUSTRIAL

OUTPUT:

INCREMENTAL

MAX RESOLUTION:

200,000 COUNTS/REV.



# ABOVE - STANDARD PERFORMANCE

The Series **9x25** is a family of optical incremental encoders designed for industrial-grade applications that require high resolution and high accuracy. All 9x25s share these features:

- LED illumination for long life (>100,000 hours)
- Differential photo-detectors for signal stability
- Single-board, surface-mount electronics for reliability
- RS-422 differential line driver output for noise immunity
- Zero index signal
- Sealed ABEC 7 bearings for contamination resistance
- IP65 sealing for harsh environments (IP64 at the shaft exit)

The Series 9x25 is available in three basic models:

- **Model 9125**: Resolutions up to 9000 cycles/rev (36,000 counts/rev); optional index formats; optional input voltage.
- Model 9225: Dual read heads for improved accuracy; ASIC for internally interpolated resolutions up to 50,000 cycles/rev (200,000 counts/rev); watchdog circuit.
- **Model 9425**: Same as **9225**, except with four read heads for highest accuracy. Each 9425 includes an accuracy plot.









## SPECIFICATIONS

Specifications	See Note	9125	9225	9425
Maximum line count on disc	6	9,000	9,000	
Max cycles/rev with internal electronics		9,000	50,000	
Max counts/rev after quad edge detect		36,000	200	,000
Instrument error, ± arcsec	1,2	45	20	10
Quadrature error, ± electrical degrees	1,3	30	24	15
Interpolation error, ± quanta	1,4	N/A	0.10	
Maximum output frequency, kHz				
1X square waves, data only		500	1	00
1X square waves, data + index		250	100	
2X square waves, data + index		N/A	150	
5X square waves, data + index		N/A	300	
10X square waves, data + index		N/A	500	
Maximum weight, oz (g)		20 (565)		
Starting torque, in-oz (N-m) @20°C	5	2.0 (14.0 x 10 <sup>-3</sup> )		
Running torque, in-oz (N-m) @20°C	5	1.0 (7.0 x 10 <sup>-3</sup> )		
Moment of inertia, in-oz-s² (g-cm²)		9.0 x 10 <sup>-4</sup> (63.2)		
Maximum acceleration, rad/s <sup>2</sup>		2 x 10 <sup>6</sup>		
Operating temperature, °F (°C)		32 to 158 (0 to 70)	32 to 122 (0 to 50)	
Storage temperature, °F (°C)		-4 to 176 (-20 to 80)		
Humidity, % RH, non-condensing		98		
Shock		50g, 11ms		
Sealing		IP65, except IP64 at shaft exit		
Bearings		Grease-lubricated and sealed		
Maximum radial shaft load, lb (N)	5	30 (133)		
Bearing life (with 10-lb radial load)		1.4 x 10 <sup>9</sup> rev		

## NOTES:

- 1. Total Optical Encoder Error is the algebraic sum of *Instrument Error* + *Quadrature Error* + *Interpolation Error*. Typically, these error sources sum to a value less than the theoretical maximum. Error is defined at the signal transitions and therefore does not include quantization error, which is ±1/2 quantum. ("Quantum" is the final resolution of the encoder, after user's 4X quadrature decode.) Accuracy is guaranteed at 20°C.
- 2. *Instrument Error* is the sum of disc pattern errors, disc eccentricity, bearing run-out and other mechanical imperfections within the encoder. This error tends to vary slowly around a revolution.
- 3. Quadrature Error is the combined effect of phasing and duty cycle tolerances and other variables in the basic analog signals. This error applies to data taken at all four transitions within a cycle; if data are extracted from 1X square waves on a 1X basis (i.e., at only one transition per cycle), this error can be ignored.

# Error in arcseconds = (3600) x (error in electrical degrees) / (disc line count)

4. Interpolation Error is present only when the resolution has been electronically increased to more than four data points per optical cycle. It is the sum of all the tolerances in the electronic interpolation circuitry.

## Error in arcseconds = (1296000) x (error in quanta) / (counts/rev)

- 5. If reduced torque or higher load capacity is required, consult factory.
- 6. With line counts ≥ 6000, operating temperature range is 32°F to 122°F (0°C to 50°C).

As part of our continuing product improvement program, all specifications are subject to change without notice.





# **SPECIFICATIONS**

#### **INPUT POWER**

**9125**: Standard: +5 ±0.25 VDC @75 mA max. Optional: +7-15 VDC **9225**, **9425**: +5 ±0.25 VDC @75 mA max.

#### **OUTPUT DEVICE**

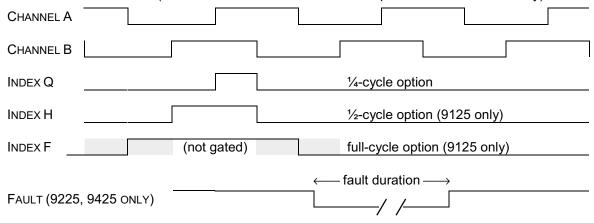
EIA/RS-422 balanced differential line driver, protected to survive an extended-duration short circuit across its output. May be used single-ended for TTL-compatible inputs.

#### **INDEX OPTIONS**

**9125**: Index is available in one of three formats: ungated full cycle wide ±180° elect; half-cycle wide, gated with high state of B; or quarter-cycle wide, gated with high states of A and B.

9225, 9425: Index is quarter-cycle wide, gated with high states of A and B.

# **OUTPUT WAVEFORMS** (Clockwise shaft rotation shown. Complements omitted for clarity)



# WATCHDOG CIRCUIT (MODEL 9225 AND 9425 ONLY)

If the 9225 or 9425 photo-detector outputs deviate beyond prescribed limits, an active-low FAULT signal is issued whose duration will be for as long as the fault condition lasts.

Fault conditions detectable by this method include operation outside the specified encoder temperature range; broken or high-impedance wiring to the encoder; LED failure; low supply voltage; badly damaged bearings; defective photo-detectors; operation beyond the rated speed; and localized code disc defects such as chips, cracks or contamination.

The watchdog output provides advance warning of gradual performance degradation in cases where the failure is not catastrophic. This gives the user an opportunity to schedule replacement of the encoder while continuing to use it, as long as it functions correctly otherwise.

# **INTERPOLATION CONSTRAINTS (9225 AND 9425 ONLY)**

Interpolation factor	Allowable line counts	Output cycles/rev	Max. output frequency
1X	200-9000	200-9000	100 kHz
2X	200-8192	400-16384	150 kHz
5X	200-6000	1000-30000	300 kHz
10X	200-5000	2000-50000	500 kHz





# **ELECTRICAL OPTIONS**

# **ELECTRICAL CONNECTIONS**

Output	Wire Colors	Pin #, Dx-15P	Pin #, DE-9P	Pin #, MS3102E-18-1P		
Functions	Conn. Code P	Conn. Code <b>Q</b> or <b>R</b>	Conn. Code <b>S</b>	Conn. Code A	Conn. Code M	
Α	Yellow	8	4	Α	Α	
/ <b>A</b>	Brown	7	8	Н	В	
В	Green	5	3	В	С	
/ B	Orange	4	7		D	
IND	Blue	2	2	С	Е	
/ IND	White	1	6	J	F	
FLT	Violet	12				
/ FLT	Gray	11				
+V	Red	10	5	D	I	
COMMON	Black	13	9	F	J	
CASE	Bare (shield)	9	1	G	Н	

# NOTES:

- 1. Channel B leads Channel A for clockwise shaft rotation, viewed from the shaft end.
- 2. FLT and /FLT signals are available with 9225 and 9425, but only with connector codes P, Q or R.

## **BEARING LUBRICANTS**

The standard lubricant, *Andok*® *C*, is specifically formulated for severe service, high speed, long life, low torque and low temperature rise; it is suitable for most applications. *Braycote*® *601EF* is a low-vapor-pressure lubricant for use in vacuum and clean-room applications at the expense of slightly higher torque.\*

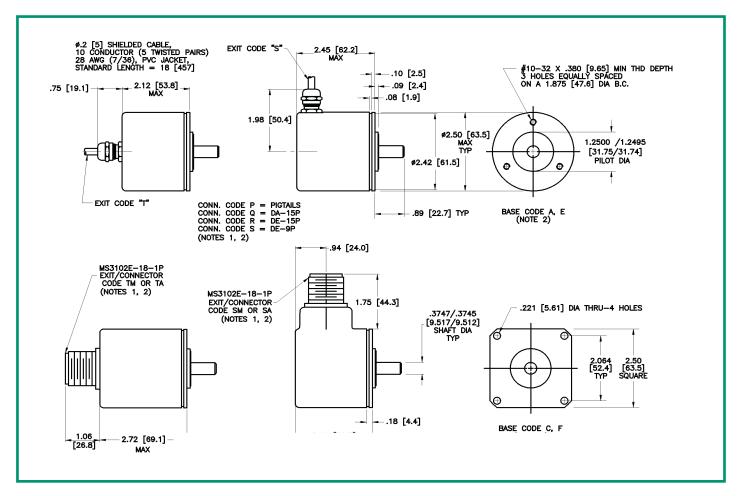
Base code	Mounting	Lubricant	
Α	Synchro/face	Andok C	
C Square-flange		Andok C	
E	Synchro/face	Braycote 601EF	
F Square-flange		Braycote 601EF	

<sup>\*</sup>Andok and Braycote are brand names of Exxon Corp and Castrol Industrial North America, respectively. GPI reserves the right to change to equivalent lubricants without notice.





# DIMENSIONS



## Notes:

1. Mating connector is optional.

Connector Code	Р	Q	R	S	М	Α
Optional mating connector	N/A	M01	M05	M06	M02	M02

- 2. Any connector code can be used with any base code.
- 3. See Rack-and-Pinion data sheet for rack details.
- 4. All dimensions are in inches [mm]





# ORDERING INFORMATION

MODEL SHAFT LINES IND V OUT INTERP BASE CAB EXIT CONN DIA **SPEC** 

**MODEL** 

9125 Standard accuracy

**9225** High accuracy

9425 Highest accuracy

**SHAFT** - Shaft type

Solid shaft

LINES - Disc line count

00200, 00250, 00300, 00360, 00500, 00600, 00635, 00900, 01000, 01200,

01250, 01720, 01800, 02048, 02400,

02500, 02540, 03000, 03125, 03600,

04096, 05000, 06000, 06282, 08192,

09000

Consult factory for other line counts.

**IND** - Index format

Full cycle ungated (9125 only)

Н Half cycle gated (9125 only)

Quarter cycle gated (any model)

V - Input voltage

5 volts dc

7-15 volts dc (9125 only)

**OUT** - Output format

RS-422 Differential line driver

**INTERP** - Interpolation factor

01 1X square waves

**02, 05, 10** 2, 5 or 10X square waves available with 9225 or 9425

BASE - Base & lubricant type

Α Synchro/face mount, Andok

С Square-flange mount, Andok

Ε Synchro/face mount, Braycote

Square-flange mount, Braycote

**CAB** - Cable length, inches

**18** Standard

00 With CONN code A, M or T

**EXIT** – Cable exit or connector location

S Side

T Top

**CONN** - Connector

Pigtails (no connector)

Q DA-15P

R DE-15P

S DE-9P

Α MS3102E-18-1P (see wiring table)

M MS3102E-18-1P (see wiring table)

Terminals; available only when used T

with HDT enclosure

**DIA** - Shaft diameter

**06E** 3/8" shaft dia

**SPEC** - Special features

Issued at time of order to cover special

customer requirements

No special features

**Accessories** (order separately)

**M01** DA-15S (mates with CONN code **Q**)

**M05** DE-15S (mates with CONN code **R**)

**M06** DE-9S (mates with CONN code **S**)

M02 MS3106E-18-1S (mates with CONN code A or M)

AX06399 Synchro mounting cleats ISC3N Interface card for IBM® PC HDT

Heavy-duty enclosure

## **SPECIAL CAPABILITIES**

For special situations, we can customize encoders to provide higher frequency response, greater accuracy, wider temperature range, reduced torque, non-standard line counts, or other modified characteristics. In addition, we regularly design and manufacture custom encoders for user-specific requirements. These range from high-volume, low-cost, limitedperformance commercial applications to encoders for high-performance, high-reliability conditions. We welcome the opportunity to help you with your special encoder needs.

## **WARRANTY**

Gurley Precision Instruments offers a limited warranty against defects in material and workmanship for a period of one year from the date of shipment.



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